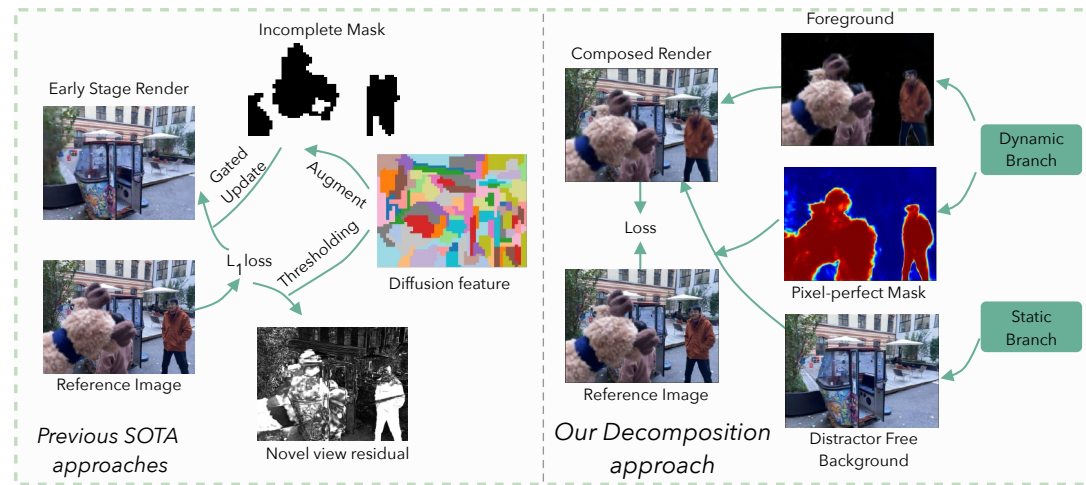


## Background

Reconstructing clean, distractor-free 3D scenes from real-world, cluttered, and dynamic captures remains challenging, especially in casual captures such as egocentric videos. To address this issue, we propose DeGauss, a decoupled foreground-background design which leverages dynamic-static Gaussian splatting for robust and generalizable dynamic-static decomposition.

## Key Insight

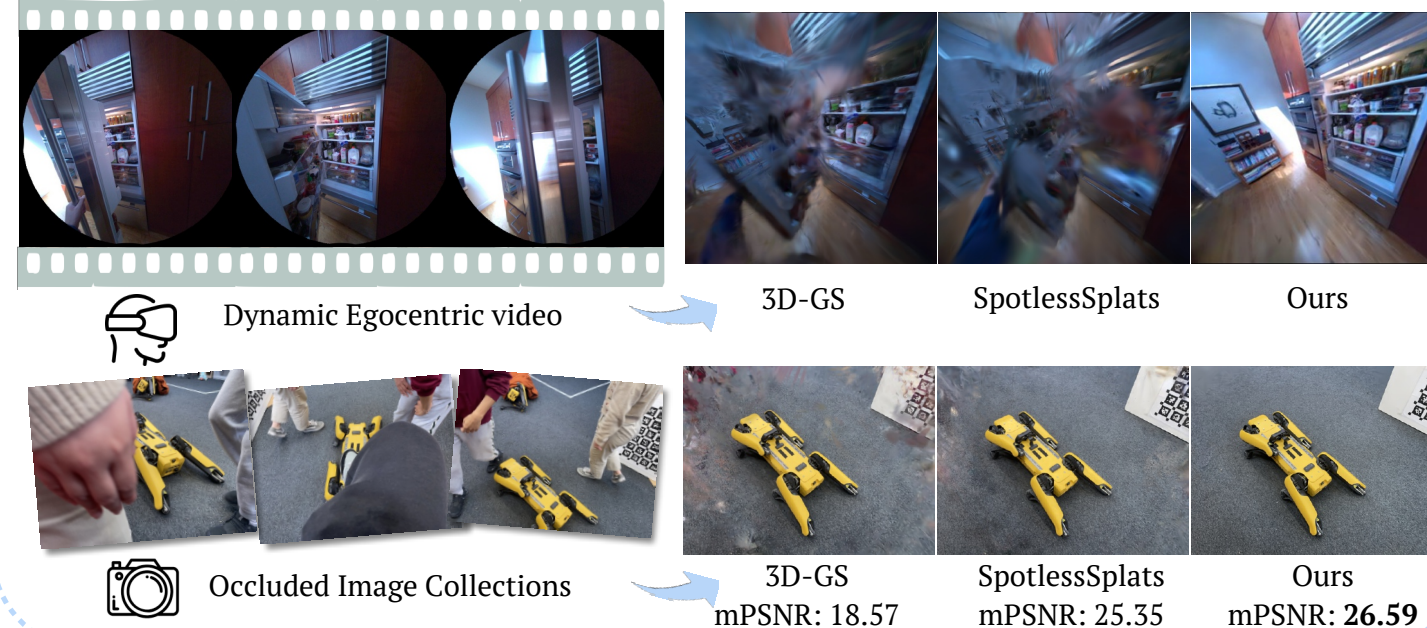
Leverage the complementary expressiveness of dynamic/static gaussians of separate branches to achieve minimum cross modeling



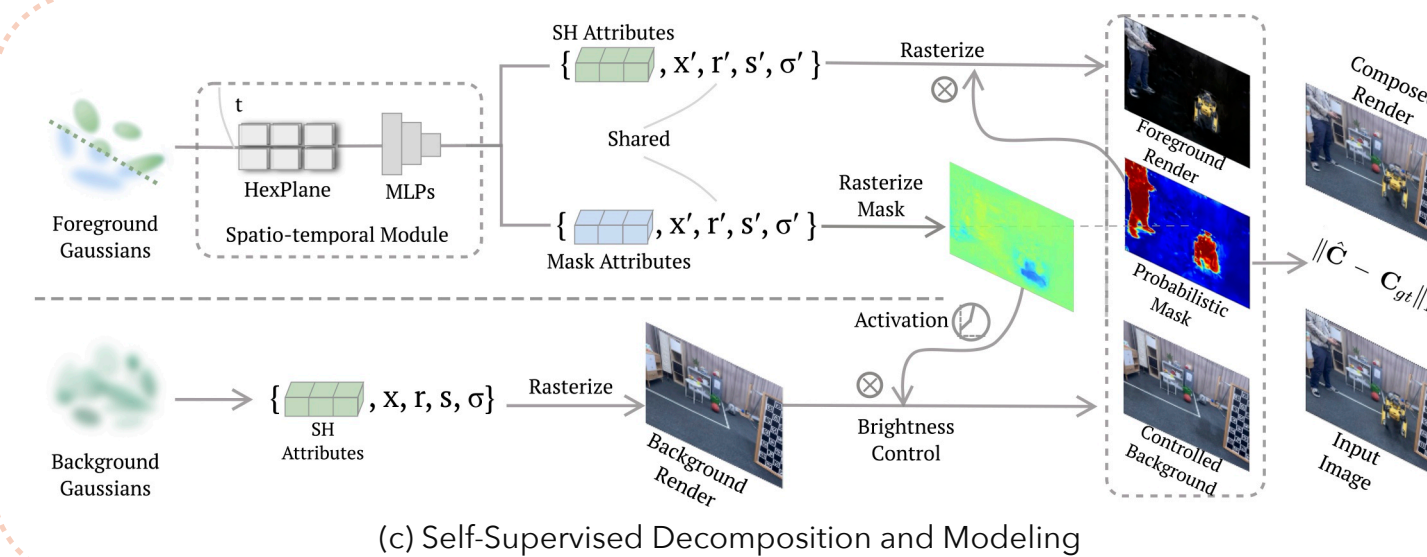
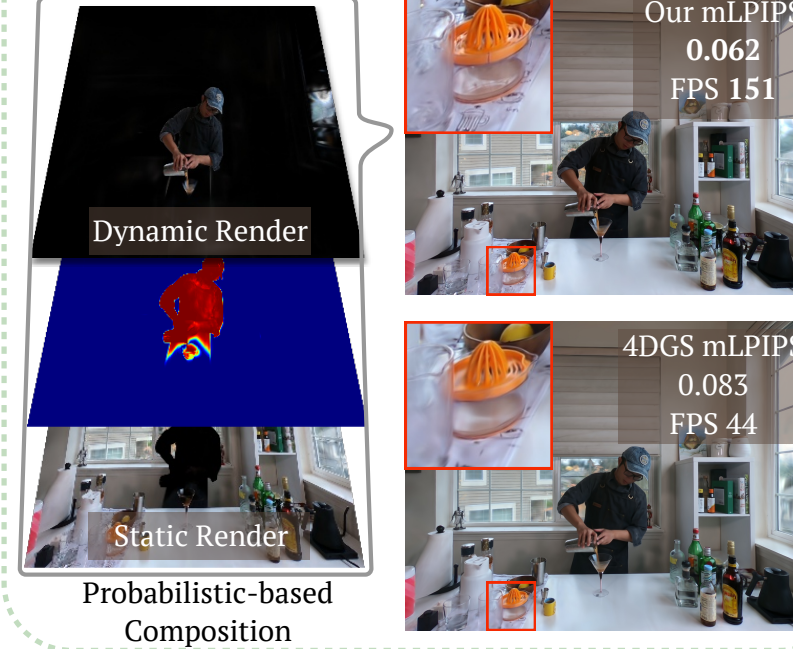
## Conclusion

- Our proposed method DeGauss achieves SOTA distractor-free reconstruction results for both highly challenging egocentric videos and image collections.
- DeGauss also enables high-quality and efficient dynamic scene modeling through the decoupled dynamic-static representation.

(a) Distractor-Free Static Scene Modeling



(b) Dynamic Scene Modeling

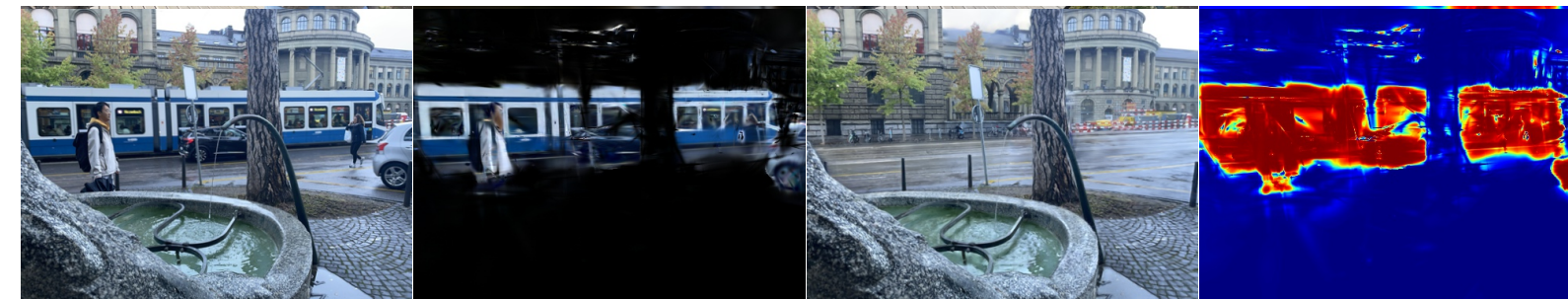


(c) Self-Supervised Decomposition and Modeling

With Self-supervised Dynamic-static decomposition based on the complementary expressiveness of foreground/background gaussian splatting (c), DeGauss models SOTA distractor-free static scene from noisy input (a) and yields high-quality & Efficient dynamic scene representation (b).

Distractor-free scene reconstruction on Nerf on-the-go dataset

Method	Mean		
	PSNR↑	SSIM↑	LPIPS↓
RobustNeRF [27]	19.64	0.583	0.369
NeRF On-the-go [26]	21.67	0.720	0.234
3DGS [13]	19.30	0.668	0.253
WildGaussian [15]	22.16	0.746	0.182
DeSplat <sup>‡</sup> [41]	<b>22.58</b>	<b>0.813</b>	<b>0.130</b>
Spotlessplats [28]	<b>23.42</b>	<b>0.813</b>	<b>0.145</b>
Ours	<b>23.91</b>	<b>0.819</b>	<b>0.113</b>



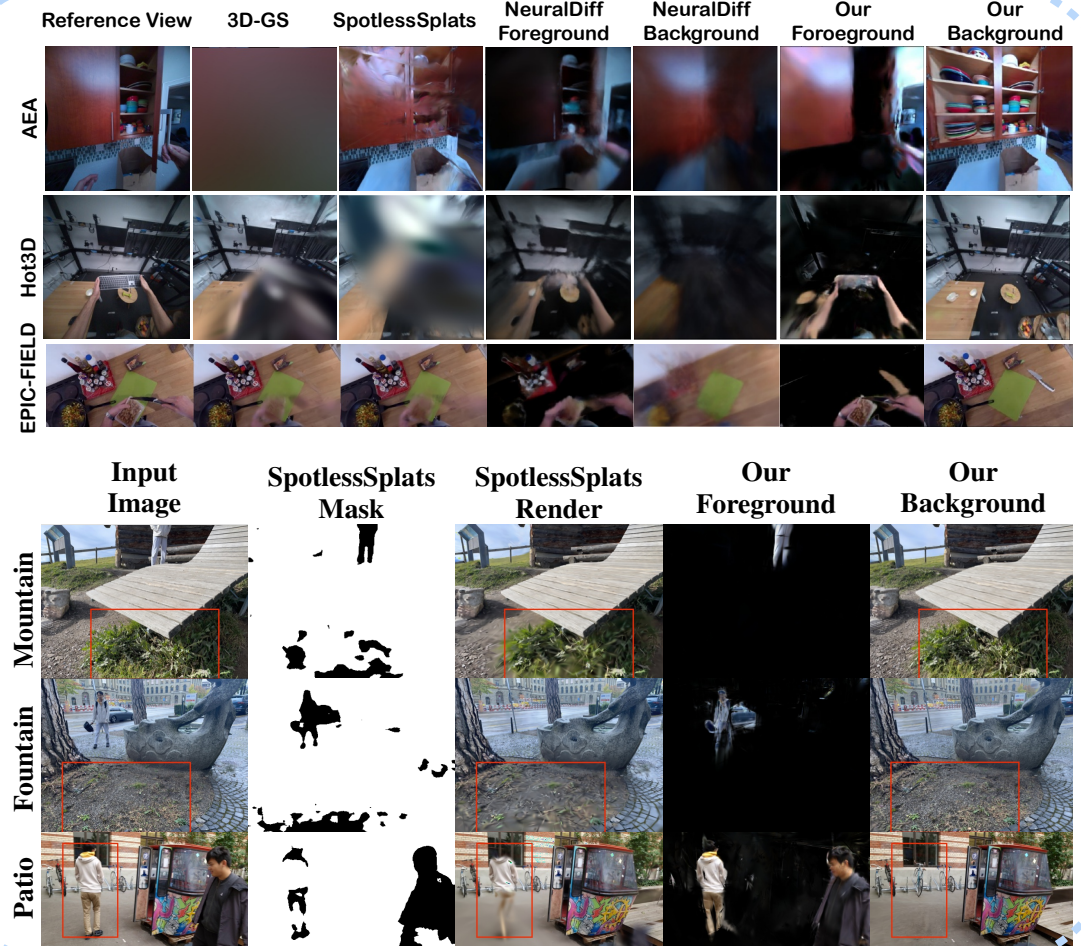
By leveraging Gaussian Splatting for Dynamic-static decomposition, we get:

Method	PSNR(↑)	SSIM(↑)	LPIPS(↓)	Training Time(↓)	FPS(↑)	Dyna. Gaussian num
NeRFPlayer [26]	30.29	0.909	0.151	6 hours	0.045	-
HyperReel [11]	30.72	0.931	0.101	9 hours	2.0	-
HexPlane [3]	30.00	0.922	0.113	12 hours	0.2	-
KPlanes [6]	<b>31.63</b>	<b>0.964</b>	0.117	5.0 hours	0.3	-
SWinGS [25]	31.12	<b>0.941</b>	0.095	-	<b>71</b>	-
4DGS [31]	31.12	0.937	<b>0.058</b>	<b>0.85 hours</b>	53	124,197
4DGS <sup>†</sup> [31]	28.72	0.919	<b>0.078</b>	<b>0.67 hours</b>	<b>68</b>	<b>62298</b>
Ours	<b>31.52</b>	<b>0.942</b>	<b>0.047</b>	2.1 hours	<b>71</b>	<b>56,533</b>
Ours <sup>†</sup>	<b>31.56</b>	<b>0.942</b>	<b>0.047</b>	2 hours	<b>157</b>	<b>22,479</b>



Efficient Dynamic Scene Reconstruction on Neu3D dataset

Distractor-Free Static Scene Recon



Efficient & High-Quality Dynamic Scene Recon

